## GBM-HONSEERG

## Product Information

OMNI-L

## Level Transmitter / Switch OMNI-L



- Ultrasound, level, and distance measurement with display
- Analog output, two switching outputs
- Compact construction
- Clear, easily legible, illuminated LCD display
- Modifiable units in the display
- Designed for industrial use
- Small, compact construction
- Very simple installation


## Characteristics

The level sensor consists of the primary sensor (an ultrasound sensor) which, contact-free, determines the separations of media of different types (fluids, transported goods, solids). The ultrasound sensor works on the principle of end-to-end measurement. Emitted ultrasound impulses are reflected at the surfaces, and return to the transducer after a transit time. The transit time is proportional to the distance. The electronics convert the transit time into a distance, and output an analog output signal proportional to the separation. The separation is displayed in cm or inch (other units available on request).

By turning the programming ring to right or left, it is simple to modify the parameters (e.g. switching point, hysteresis...). To protect from unintended programming, it can be removed, turned through $180^{\circ}$, and replaced, or completely removed, thus acting as a key.


## Technical data

| Sensor | ultrasound transmitter / receiver |
| :---: | :---: |
| Mechanical Connection | 3-hole flange |
| Metering ranges | 1.5 m or 2.5 m |
| Sound beam | 8 degrees |
| Measurement accuracy | $\pm 0.2$ \% FS |
| Linearity error | < 0.3 \% FS |
| Temperature error | $0.03 \% /{ }^{\circ} \mathrm{C}$ |
| Working temperature | $0 . .70^{\circ} \mathrm{C}$ |
| Storage temperature | $-20 . .+80^{\circ} \mathrm{C}$ |
| Supply voltage | $18 . .30 \mathrm{~V}$ DC |
| Power consumption | < 3 W |
| Analog output | $\begin{array}{\|l\|} \hline 0 / 4 . .20 \mathrm{~mA} \\ \text { (0/2..10 V available on request) } \end{array}$ |
| Switching output | transistor output "push-pull" (resistant to short circuits and polarity reversal) $\mathrm{I}_{\text {out }}=100 \mathrm{~mA} \text { max. }$ |
| Hysteresis | adjustable, position of the hysteresis depends on minimum or maximum |
| Display | backlit graphical LCD-Display (transreflective), extended temperature range $-20 . .+70^{\circ} \mathrm{C}, 32 \times 16$ pixels, background illumination, displays value and unit, flashing LED signal lamp with simultaneous message on the display. |
| Electrical connection | for round plug connector M12x1, 5-pole |
| Materials medium-contact | PET 30 \% fibreglass, epoxy resin, POM |
| Materials, non-medium-contact | housing stainless steel 1.4305 <br> mlass <br> mineral glass, <br> hardened  <br> magnet samarium-Cobalt <br> ring POM |
| Ingress protection | IP 67 |
| Weight | approx. 0.3 kg |
| Conformity | CE |

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## Product Information

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## Wiring

Z = Load


Connection example: PNP NPN


The switching outputs are self-configuring, depending on whether they are connected as PNP or NPN switches (push-pull). It is recommended to use shielded wiring.

## Dimensions



A gooseneck (optional) between the electronics head and the primary sensor provides freedom in the orientation and reading direction of the sensor.

## Handling and operation

## Installation

A $\varnothing 35.5$ hole and fixing drillings (see "Dimensions") must be broken through for the supplied stainless steel bolts (self-cutting). The separation from the container's outer wall must be taken into account (reflection!) The ultrasound cone must normally opened vertically with the surface of the material being measured. The sensor's dead zone must be taken into account (see also example for fixing). Variations in measured values (e.g. due to movement from agitators) may be masked by the use of filter times on the device.

Dead zone


Possible arrangement of the sensors
It should be noted that the sensor has a limited working range (dead zone). This may mean that in some circumstances the sensor must be mounted relatively high in order to ensure the minimum separation from the measured material, and to avoid incorrect measurements. One possibility of reducing the installation height is the diversion of the ultrasound signal to a reflection surface in front of the sensor (see diagram).

Wave slap, and surfaces which are too steep to the surface of the level to be measured should be avoided. Temperatures $>60^{\circ} \mathrm{C}$ at the measured surface may result in deviations in accuracy (here, a ventilated or aspirated submersion tube can help). Aspiration


High dust levels reduce the ultrasound signal and produce incorrect measurements. Depending on density, foams may or may not be recognised.

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## Programming

The annular gap of the programming ring can be turned to positions 1 and 2. The following actions are possible:


Set to 1 = continue (STEP)
Set to 2 = modify (EDIT)
Neutral position between 1 and 2

The ring can be removed to act as a key, or turned through $180^{\circ}$ and replaced to create a programming protector.
Operation is by dialog with the display messages, which makes its use very simple. Starting from the normal display (currently measured value with unit), if 1 (STEP) is repeatedly selected, then the display shows the following information in this order:

## Display of the parameters, using position 1

- Switching value S 1 (switching point 1 in the selected unit)
- Switching characteristic of S1
- (MIN = monitoring of minimum value, hysteresis greater than switching value,
- MAX = monitoring of maximum value, hysteresis less than switching value)
- Hysteresis 1 (hysteresis value of $S 1$ in the set unit)
- Switching value S2
- Switching characteristic of S2
- Hysteresis 2
- Code:

After entering the code 111, further parameters can be defined:

- Filter (settling time of the display and output)
- Units: e.g. $\mathrm{I} / \mathrm{min}$ or $\mathrm{m}^{3} / \mathrm{h}$
- Output: $0 . .20 \mathrm{~mA}$ or $4 . .20 \mathrm{~mA}$
- 0/4 mA (flow rate corresponding to 0/4 mA)
- 20 mA (flow rate corresponding to 20 mA )


## Edit, using position 2

If the currently visible parameter is to be modified:

- Turn the annular gap to position 2, so that a flashing cursor appears which displays the position which can be modified.
- By repeatedly turning to position 2, values are increased; by turning to position 1, the next digit is reached.
- Leave the parameter by turning to position 1 (until the cursor leaves the row); this accepts the modification.
- If there is no action within 30 seconds, the device returns to the normal display range without accepting the modification.

The limit switches S1 and S2 can be used to monitor minimal or maximal. With a minimum-switch, falling below the limit value causes a switchover to the alarm state. Return to the normal state occurs when the limit value plus the set hysteresis is once more exceeded.


With a maximum-switch, exceeding the limit value causes a switchover to the alarm state. Return to the normal state occurs when the measured value once more falls below the limit value minus the set hysteresis.


The change to the alarm state is indicated by the integrated red LED and a cleartext in the display.
While in the normal state the switching outputs are at the level of the supply voltage; in the alarm state they are at 0 V , so that a wire break would also display as an alarm state at the signal receiver.
Overload of the switching output is detected, indicated on the display ("Check S1 / S2"), and the switching output is switched off.

## Simulation mode

To simplify commissioning, the sensor supports a simulation mode for the analog output. It is possible to create a programmable value in the range $0 . .26 \mathrm{~mA}$ at the output (without modifying the process variable). This allows the wiring run between the sensor and the downstream electronics to be tested during commissioning. This is mode is accessed by means of code 311.

## Overload display

Overload of the switching output is detected, indicated on the display, and the switching output is set to high impedance.

## Product Information

## Default setting

After setting the configuration parameters, they can be reset to factory values at any time, by means of code 989.

Starting from the normal display (current total and unit), if 1 (STEP) is selected repeatedly, then the display shows the following information:

## Display of the parameters, using position 1

- Switching values S 1 and S 2: Switching values in the selected unit.
- Hysteresis direction of S 1 and S 2:

Max = Hysteresis less than S 1 or S 2

- Max = Hysteresis greater than S 1 or S 2
- Hystereses Hyst 1 and Hyst 2:
- Hysteresis values of the switching values in the set unit
- After entering code 111, further parameters can be defined (this should take place only if necessary)
- Filter: Selectable filter constants in seconds (affects display and output)
- Unit: e.g. bar or psi ...
- Output: $0 . .20 \mathrm{~mA}$ or $4 . .20 \mathrm{~mA}$
- 0/4 mA: Displayed value for 0/4 mA
- 20 mA : Displayed value for 20 mA


## Edit, using position 2

- If the visible parameter is to be modified:
- Turn the annular gap to position 2, so that a flashing cursor appears which displays the position which can be modified. By repeatedly turning to position 2 , values are increased; by turning to position 1, the next digit is reached. In this way, every digit can be modified. If there is no action within 5 seconds, the device returns to the normal display range without accepting the modification.


## Saving the changes using position 1

- After leaving the last value, turn once to position 1; this accepts the modification.


## Ordering code


O=Option

| 1. | Range |  |
| :--- | :--- | :--- |
|  | 15 | $200 . .1500 \mathrm{~mm}$ |
|  | 25 | $300 . .2500 \mathrm{~mm}$ |
| 2. | Output signal |  |
|  | I | current output $0 / 4 . .20 \mathrm{~mA}$ |
|  | U $\quad$ O | voltage output $0 / 2 . .10 \mathrm{~V}$ (available on request) |
| 3. | Optional |  |
|  | S | for round plug connector M12x1, 5-pole |
| 4. | Optional |  |
|  | H $\quad$ O | model with gooseneck |

## Accessories

- Cable/round plug connector (KB...) see additional information "Accessories"
- Device configurator ECI-1

